

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

1-11. (Canceled)

12. (Previously presented) An apparatus, comprising:

a capture mechanism configured to engage a peripheral device, the capture mechanism having a grasping member and an actuator, the actuator being configured to actuate the grasping member in response to a movement of the peripheral device, the coupling mechanism being configured to move in response to the movement of the peripheral device when the peripheral device is engaged by the capture mechanism; and

a sensing assembly configured to detect a manipulation of the peripheral device while the peripheral device is engaged by the capture mechanism.

13. (Previously presented) The apparatus of claim 12, wherein the grasping member has a tubular shape.

14. (Previously presented) The apparatus of claim 12, the grasping member being a tubular grasping member, wherein the actuator further includes:

a spring configured to elongate and compress the tubular grasping member in response to movement of the peripheral device such that the cross-sectional dimension of the tubular grasping member is adjusted.

15. (Previously presented) The apparatus of claim 12, the grasping member being a tubular grasping member, wherein the grasping member further includes:

a spring configured to elongate and compress the tubular grasping member in response to movement of the peripheral device such that the cross-sectional dimension of the tubular grasping member is adjusted, the grasping member being configured to engage the peripheral device in response to the elongation of the tubular member and being configured to release the peripheral device in response to the compression of the tubular member.

16. (Previously presented) The apparatus of claim 12, wherein the capture mechanism is disposed within the sensing assembly.

17. (Previously presented) The apparatus of claim 16, wherein the capture mechanism further includes:

a plurality of jaws configured to surround and engage the peripheral device.

18. (Previously presented) The apparatus of claim 12, wherein the capture mechanism has a plurality of jaws; and wherein the actuator further includes:

a spring configured to bias the plurality of jaws in a closed position, at least a portion of the grasping member being disposed within the spring;

a semi-conical expander disposed proximate to the spring and configured to manipulate the plurality of jaws between the closed position and an open position; and

an actuator disposed proximate and being coupled to the semi-conical expander.

19. (Previously presented) The apparatus of claim 12, wherein the capture mechanism has a plurality of jaws; and wherein the capture mechanism further includes:

an automatic capture-and-release mechanism configured to automatically actuate the plurality of jaws to engage the peripheral device.

20. (Previously presented) The apparatus of claim 12, wherein the capture mechanism has a plurality of jaws, the plurality of jaws of the capture mechanism are actuated by a force applied by a lever associated with a movement of the peripheral device.

21-33. (Canceled)